

Paper 10574-21

Session 4: Machine Learning, 3:30 PM - 5:30 PM, Salon B



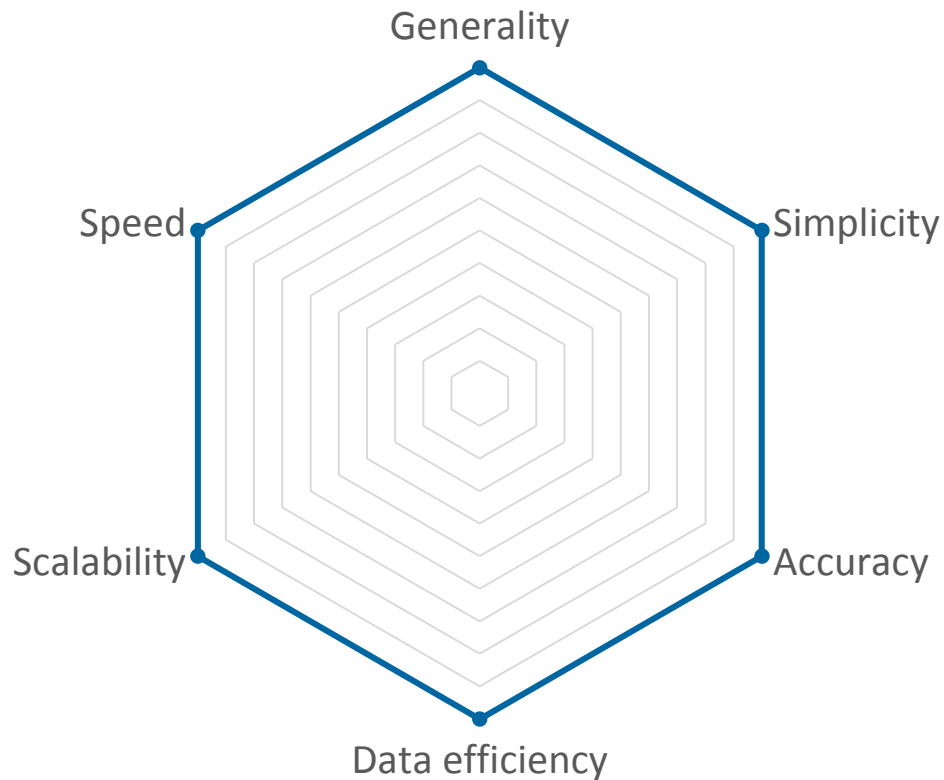
Nearest Neighbor 3D Segmentation with Context Features

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Philips Research Hamburg, Digital Imaging

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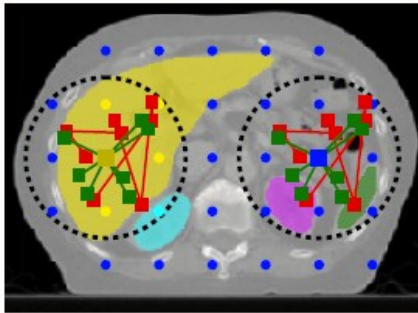
Intro / Objectives



- Automated 3D segmentation
- Supervised machine learning
- Binary context features
- Nearest neighbors classification
 - Vantage point trees
- Benchmark variations
 - Speed up

Nearest Neighbor Segmentation Pipeline

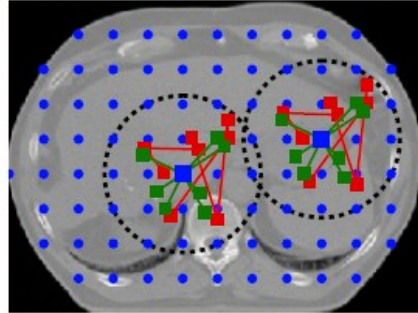
Training



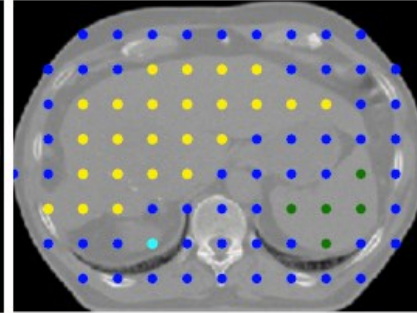
Training Features
Extraction

Binary Context
Features

Testing

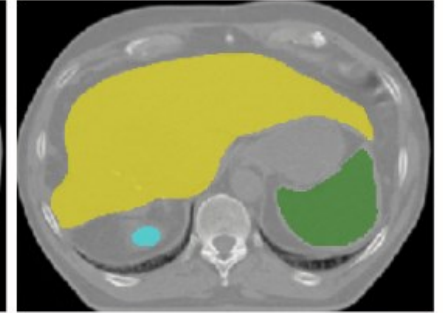


Test Features
Extraction



NNs Search
Labelling

Vantage Point
Trees



Label Interpolation
Post Processing

Binary Context Features

Random selection of coordinates around central pixel

Pairwise **intensity** comparisons

$$\tau(p; x, y) := \begin{cases} 1 & \text{if } p(x) > p(y) \\ 0 & \text{otherwise} \end{cases}$$

$p(x)$ is the **intensity** of p at a point x

Repeat n_d times (e.g. $n_d = 1280$),
form a **vector** $\mathbf{f}$:

$$f_{n_d}(p) := \sum_{i=1}^{n_d} 2^{i-1} \tau(p; x_i, y_i)$$

$p(x_i) > ? p(y_i)$



BRIEF

Binary Robust
Independent
Elementary Features

LBP

Local Binary
Pattern



Capture contextual and structural information



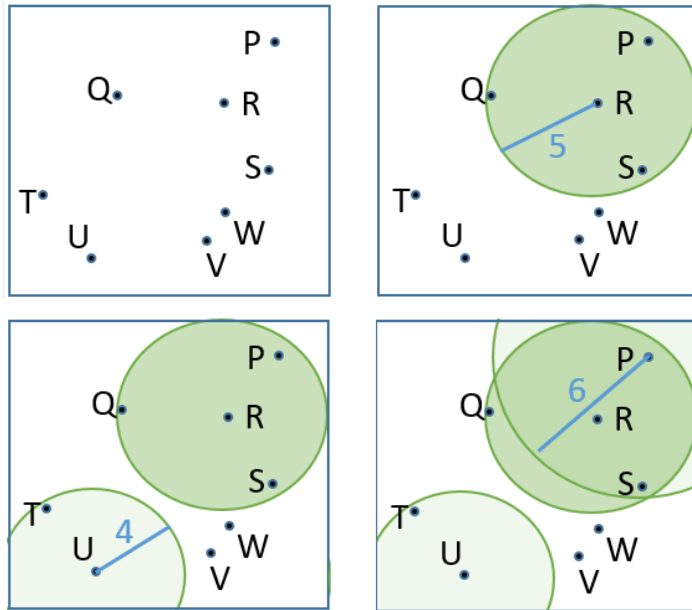
Computational efficiency (Hamming distance)



Robustness to monotonic gray-level changes

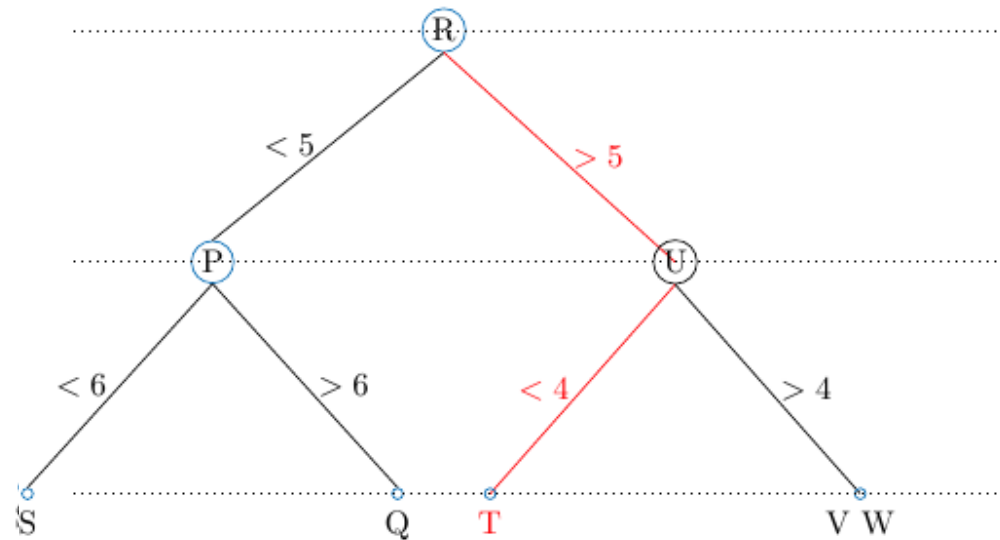
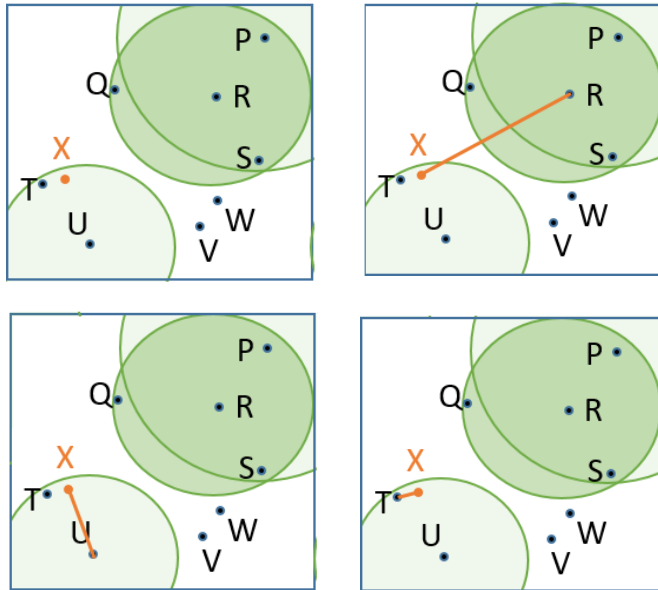
Nearest Neighbor Search

Vantage Point Trees (Construction)



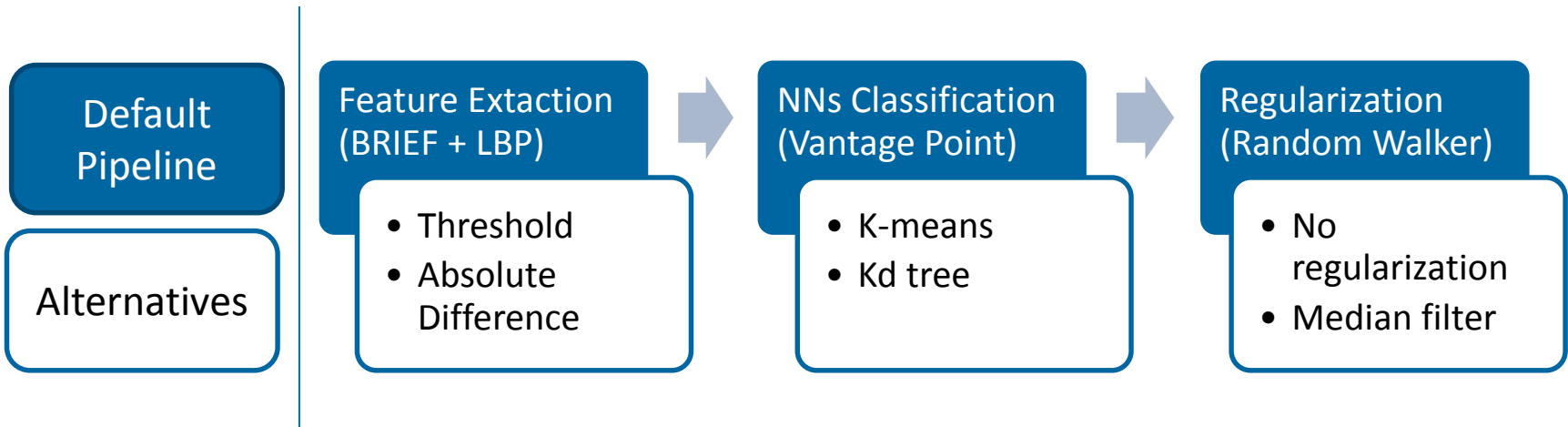
Nearest Neighbor Search

Vantage Point Tree (Query)



- ✓ Efficient NN search for binary data
- ✓ Query **k**NN → Probability maps for each label

Experiments



70 abdominal CT images

Liver, spleen, left kidney, right kidney

512 x 512 x 394 (1.36 x 1.36 x 1.35 mm)

5-fold cross validation (Train 56 / Test 14)

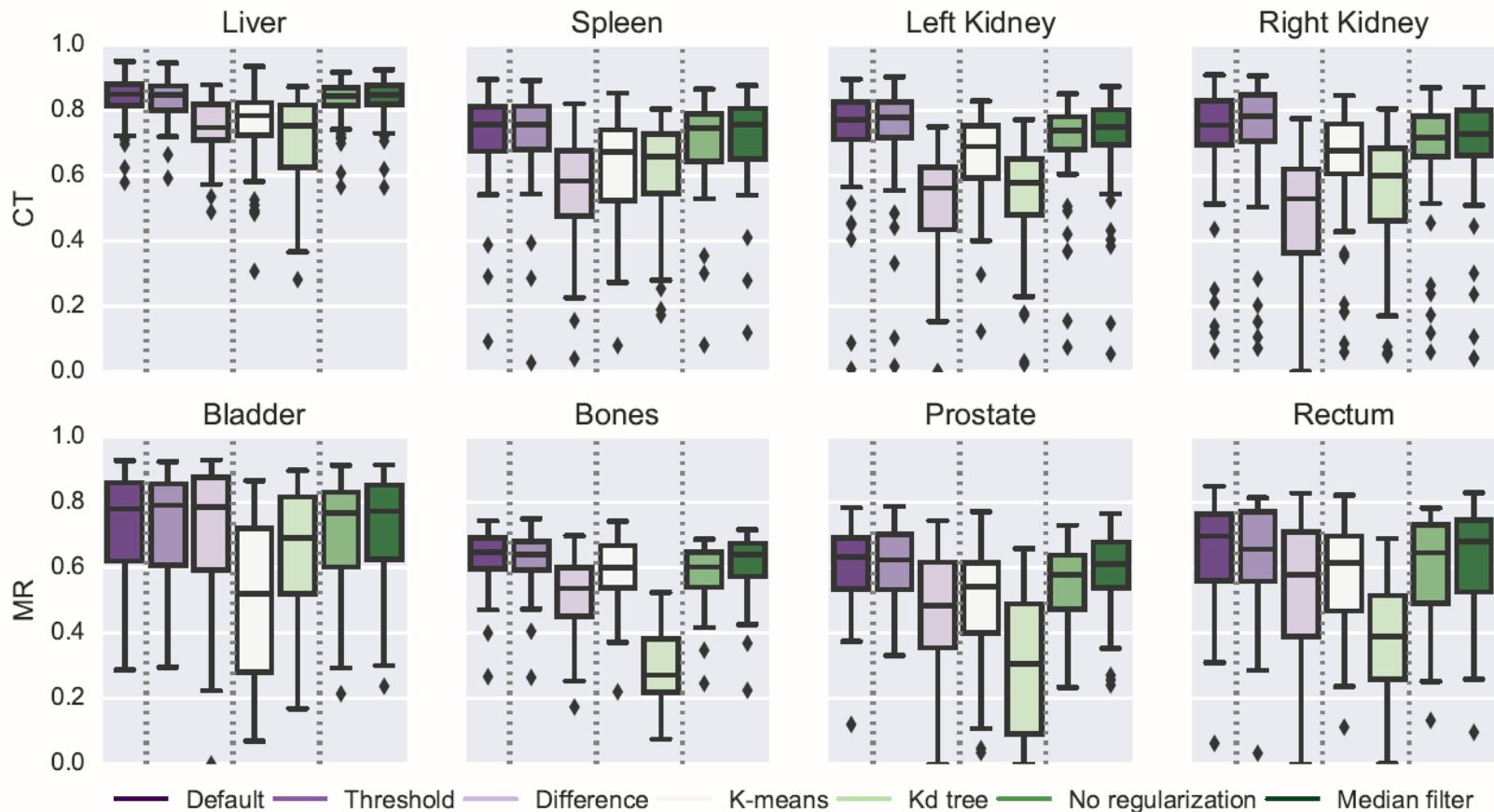
42 pelvic MR images

Bladder, bones, prostate, rectum

528 x 528 x 120 (1.04 x 1.04 x 2.5 mm)

7-fold cross validation (Train 36 / Test 6)

Results, Dice Score



Default

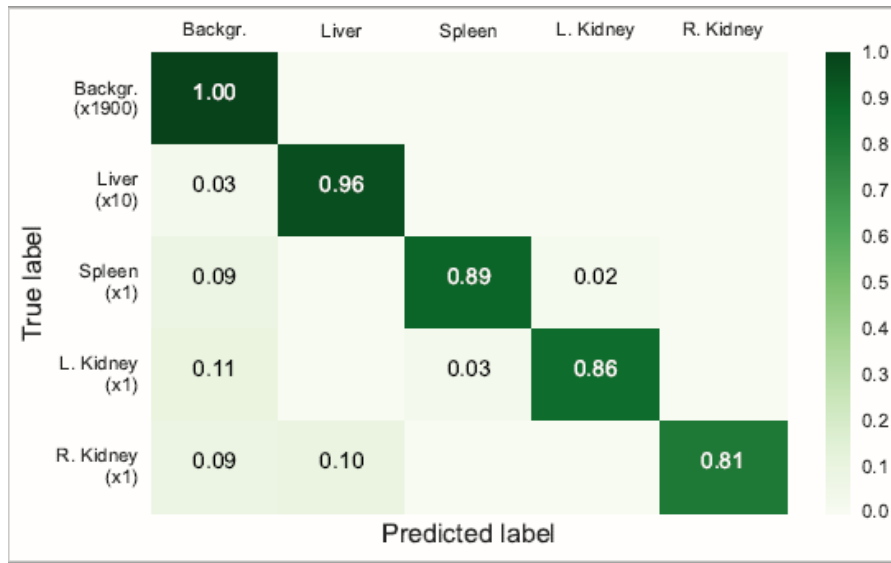
Liver: 0.84, Spleen: 0.73, L. Kidney: 0.73, R. Kidney: 0.72
Bladder: 0.73, Bones: 0.63, Prostate: 0.61, Rectum: 0.64

No regularization

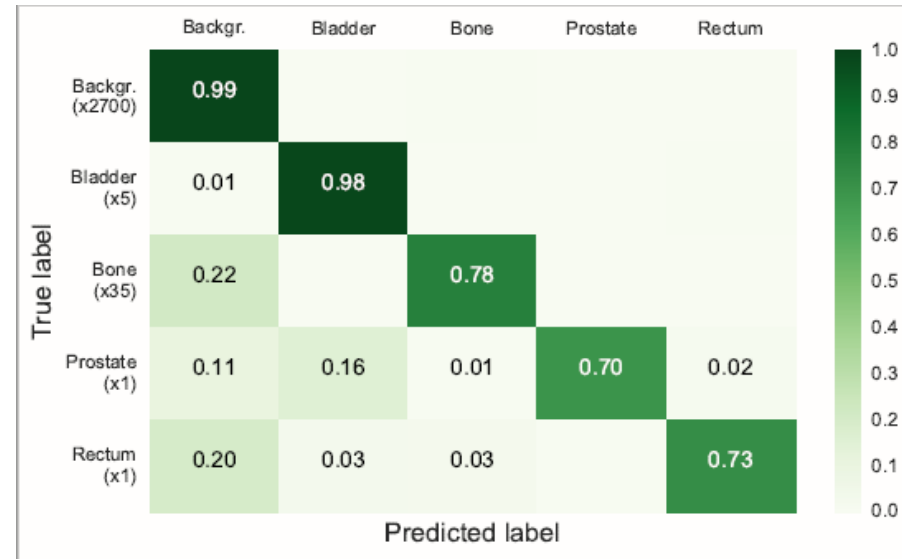
CT: 47% faster
MR: 27% faster

Results, Confusion Matrix

CT

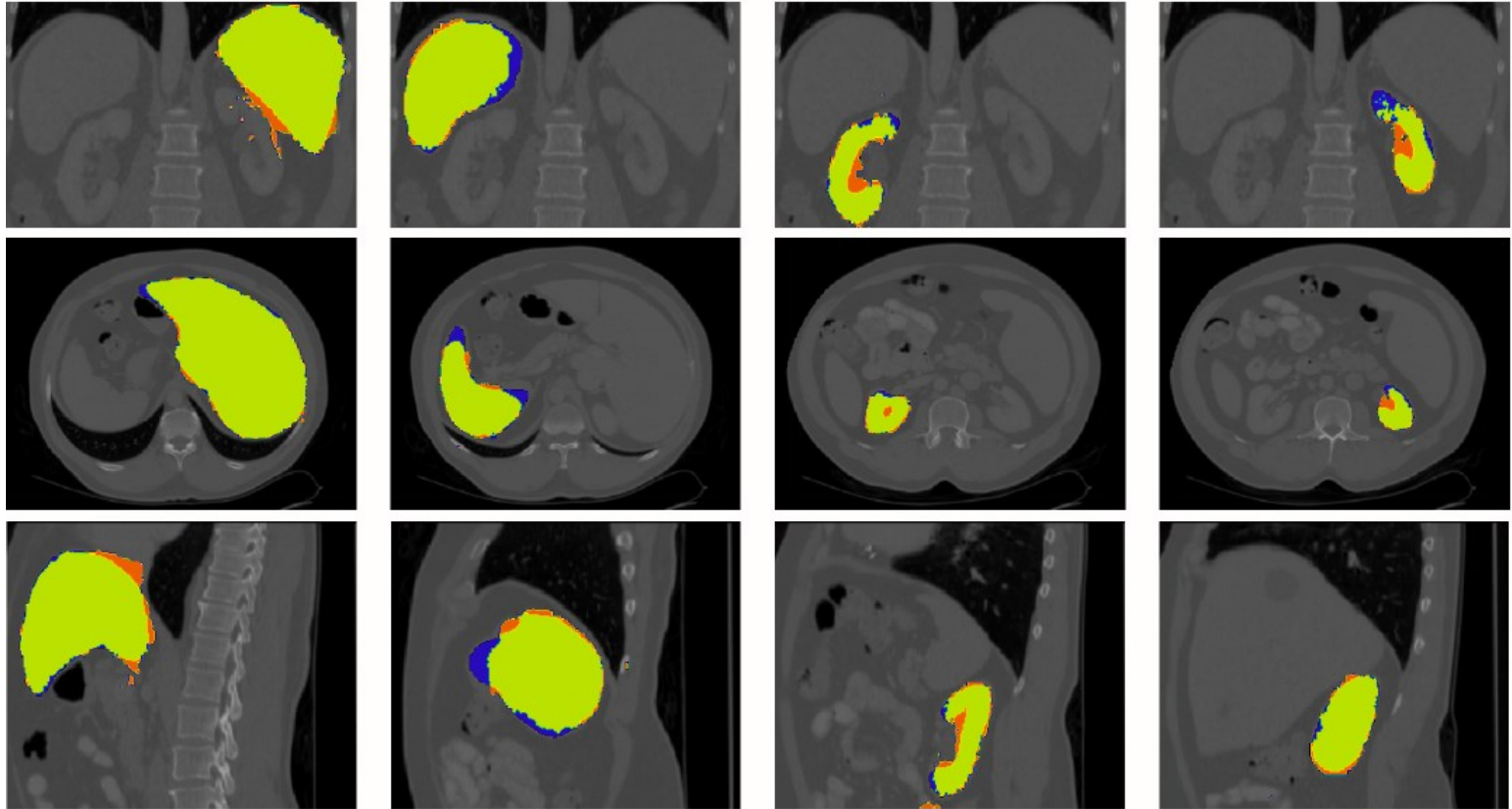


MR



- ✓ Mainly correct predictions
- ✓ Few inter-organ confusions
- ✗ Often confusion with background (imbalanced training data)

Algorithm vs. Ground Truth (CT)



Liver: 0.95

Spleen: 0.89

Left Kidney: 0.85

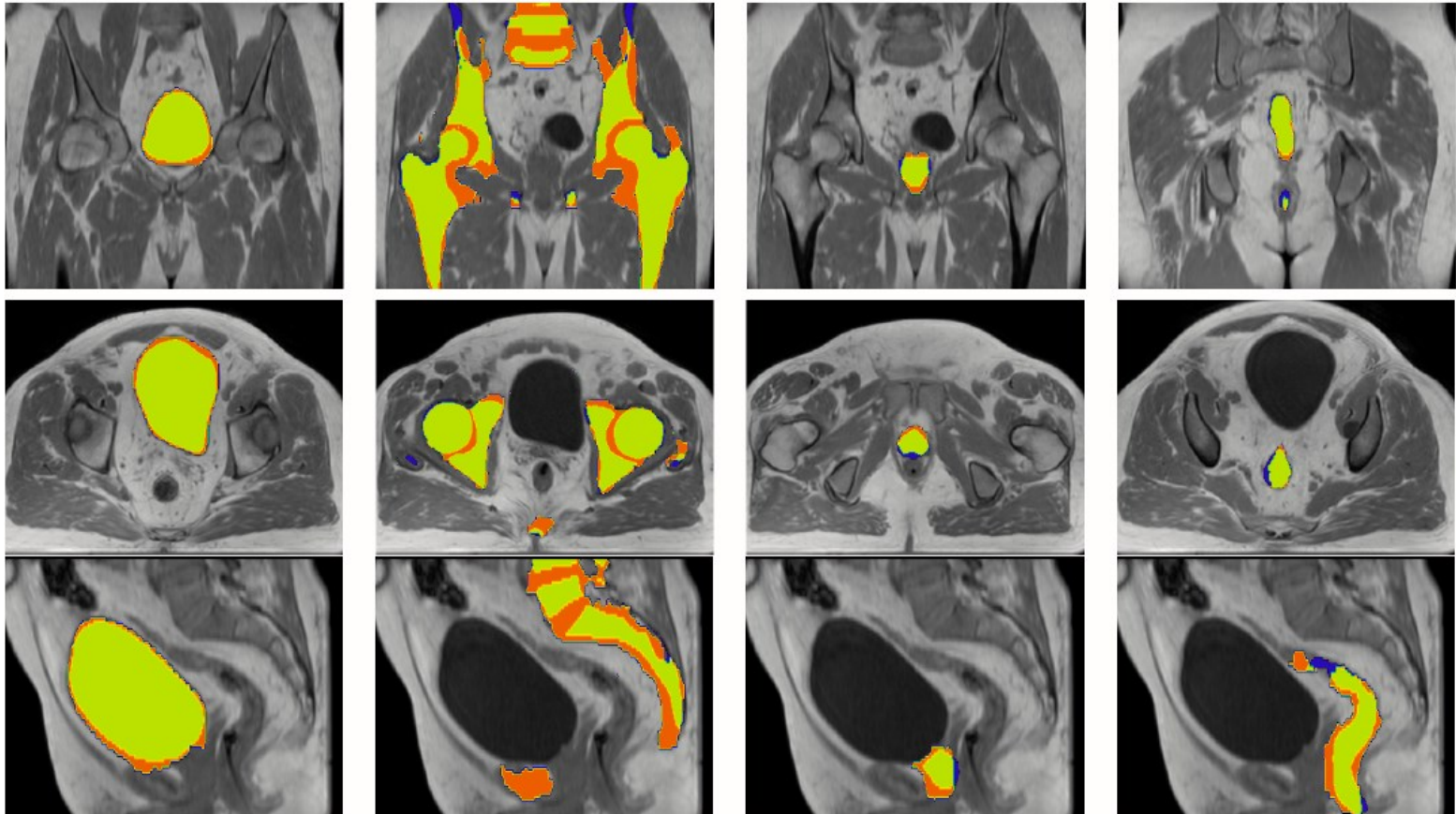
Right Kidney: 0.86

TP

FN

FP

Algorithm vs. Ground Truth (MR)



Bladder: 0.91

Bones: 0.72

Prostate: 0.66

Rectum: 0.77

TP

FN

FP

In a nutshell..

Binary Context Features

+

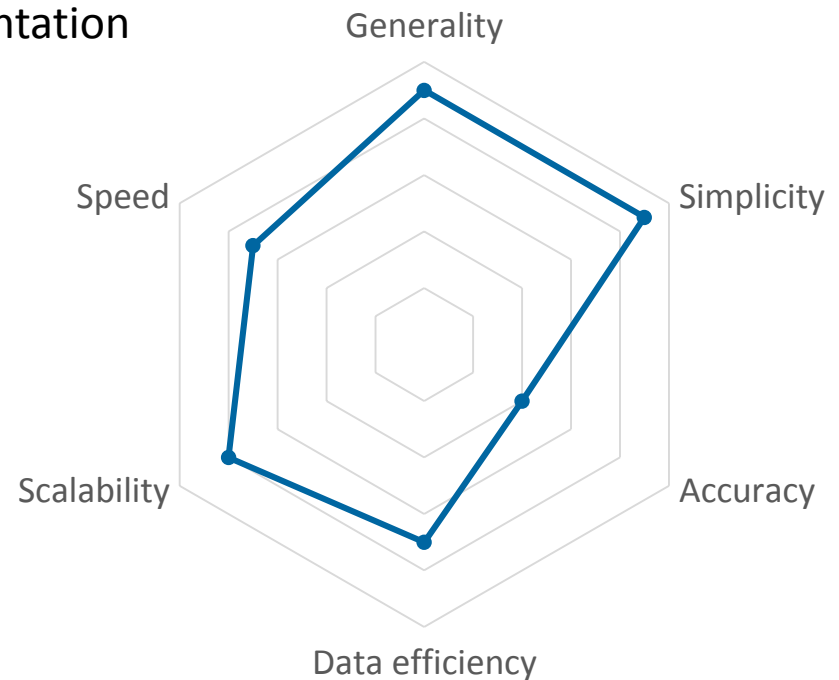
Nearest Neighbors

=

Generic, simple, data-efficient, fast segmentation

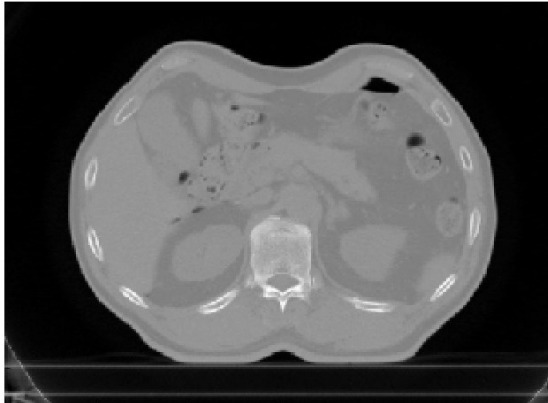
Accuracy, room for improvement

Dice: CT - 0.76, MR - 0.65

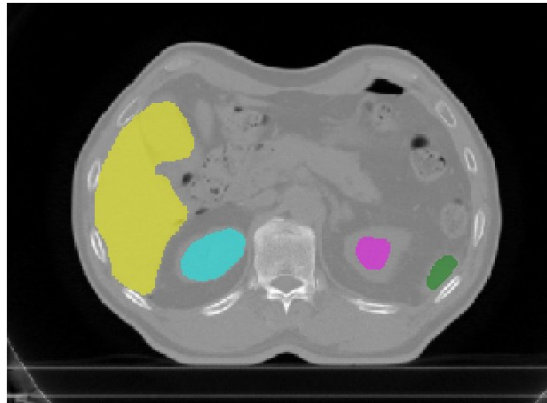




Training phase



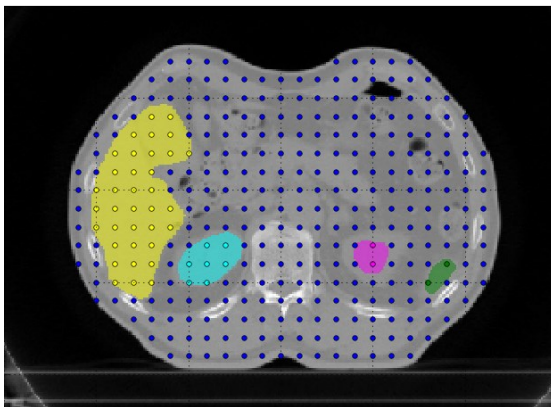
Training image



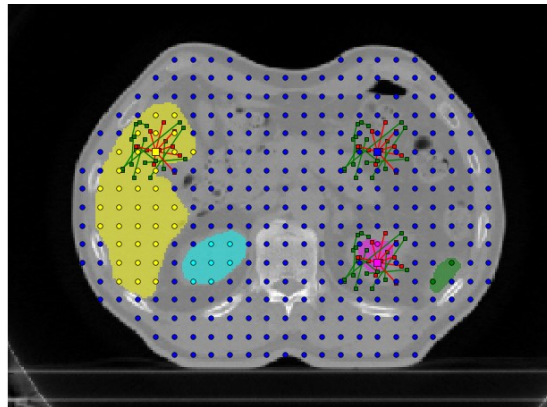
Ground truth labels



Body contour mask



Sampling grid

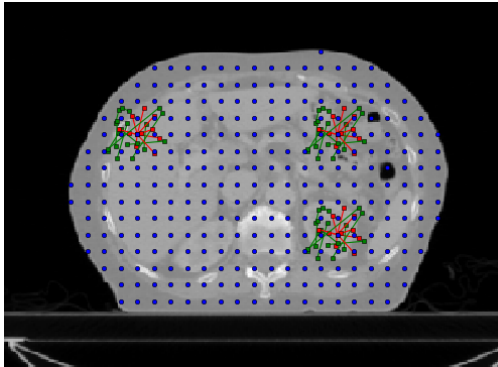


BRIEF & LBP features extraction

Feature \ Index	Index									
	0	1	2	3	4	5	6	7	...	
n=0	0	1	1	1	0	1	0	1	...	
n=1	0	1	0	0	0	1	0	0	...	
⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	...	
n=1280	0	0	1	1	0	0	1	1	...	
Label										

Storing features & labels

Test phase



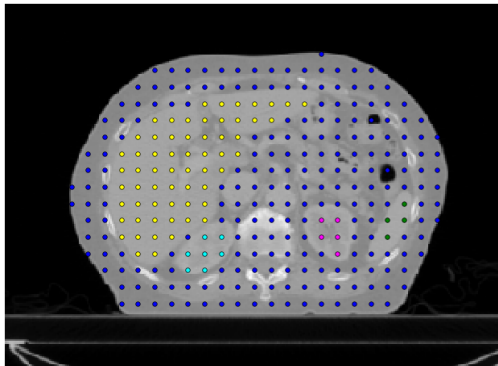
BRIEF & LBP features extraction

Index	0	1	2	3	4	5	6	...
n=0	0	1	1	1	0	0	0	...
n=1	0	1	0	1	0	1	0	...
⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮
n=1280	1	0	0	0	1	0	0	...

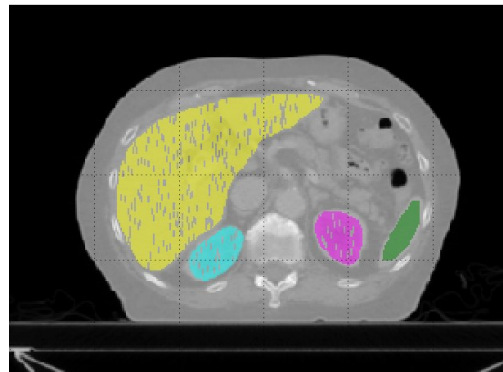
Storing test features

Index	0	1	2	3	4	5	6	...
NN = 1	0	2	1	33	34	18	3	...
NN = 2	8	63	9	13	27	29	55	...
NN = 3	12	99	26	77	33	0	56	...
NN = 4	5	14	8	9	13	1	57	...
Labels								...

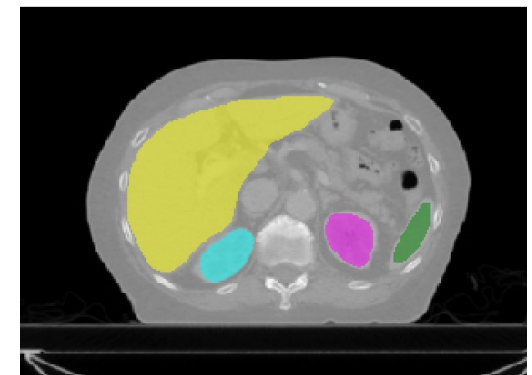
VPF NNs query, retrieve labels



Grid labels assignment



Label interpolation



Regularization